

Problem. Solved.



Stephen Balakirsky

Chief, Robotic Systems and Technologies Branch

Verification Challenges

- 1. Ability to evaluate human trust in combination with autonomous system performance
- 2. Ability to inject virtual targets/objects in parallel with the live environment to evaluate system responses to dangerous scenarios in a safe and efficient manner
- 3. Ability to discover scenarios/sequences that trigger emergent or unanticipated behavior

More Challenges

- 4. Ability to measure and quantify an autonomous system's experience level and adjust expected test outcomes
- 5. Ability to evaluate autonomy's understanding of human intent and awareness (man-machine collaboration)
- 6. Ability to evaluate autonomy's response to adaptive and intelligent adversaries (think military or highway driving[©])



Introspection is Key

 Key to all of these abilities is a standardized, consistent interface to examine the internal decision making and knowledge store of the autonomous system